Robot Arm Programmer - April 16, 1989

non-button

```
forward        forward        forward
left                          right
        \        |        /
stop  —  ( stop )  — stop
        /        |        \
reverse        reverse      reverse
left           right         right
```

button

```
arm            pinch         wrist
up                            up
        \        |        /
stop  —  ( stop )  — stop
        /        |        \
arm                         wrist
down           turn          down
```
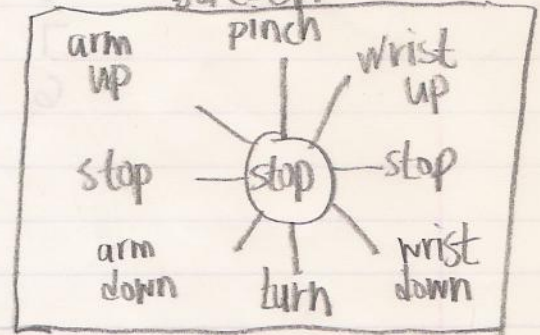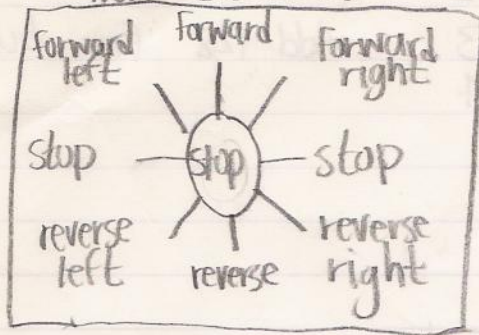
12 movements + 1 stop = 13 movements
need to Dim T(200), M(200) ← — Time in tenths of second.

        Step ⌐   ⌐ movement

Space bar - starts and stops timing sequence
F1 - does recall
F3 - saves recall
F5 - loads recall
F7 - toggles real time mode
← - toggles autobraking

Robot De-activated
Standby Mode On

[ROBOT] (3-times)
Standby Mode Off
Robot Activated
Main Menu
| MOVE | SELECT | ROBOT |

Select Menu
| ROTATE | ENTER | DONE |

	ARM	WRIST	WHEEL [LEFT RIGHT BOTH]
Motor			
Direction	UP DOWN	UP DOWN TWIST CLAMP	FORWARD REVERSE
Duration	ROTATE	ENTER DONE	

Group 1	POINT	ZERO	ONE TWO
Group 2	THREE	FOUR	FIVE SIX
Group 3	SEVEN	EIGHT	NINER SCRATCH

Please Verify _____
| YES | NO |